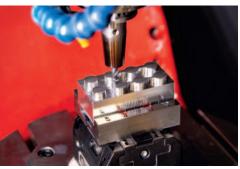


### EMCO'S FLEXLOADER ENSURES HIGH PRODUCTIVITY AND OPTIMISED PRODUCTION PROCESSES

FlexLoader robot cells by EMCO are standardised and flexible machine tool automation solutions for improved production processes and increased efficiency.

EMCO's innovative machine tools are accompanied by increasing demands on a more intelligent and more flexible type of robot automation. Featuring state-of-theart technology, all FlexLoader robot cells are standardised and designed to meet the increasing demands on flexible and costeffective production processes.



Profit milling with Esprit TNG

#### ADVANCED AND YET EASY TO OPERATE

The robot is controlled and communicated with via the software, which allows for intuitive programming when it comes to the setup of new workpieces. With this flexible and easy-to-operate system, it is possible to complete the teach-in of a new workpiece in less than 10 minutes.



#### DEGREE OF UTILISATION / EFFICIENT MACHINE TOOL INVESTMENTS

When opting for robot automation, it is possible to increase the machine utilisation by 60% compared to manual loading. This results in a short payback period for the company.



/ Peter Koren EMCO Product Sales Manager Automation

"This customised EMCO solution is the perfect synergy between robotics and camera technology – smart, flexible and with a quick ROI."



**OPTIMAL CAPACITY** UTILISATION

> The combination of robot and machine tool results in a capacity utilisation of more than 90% (manual loading: approx. 50%).

### CUSTOMISED SOLUTIONS WITH WELL-ENGINEERED PRODUCTS

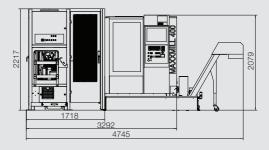
- / Standard cells and function packages
- / Optional extras (deburring station, gripper exchange, measuring units and much more)
- / Illustration of the entire process
- / Everything from a single source one contact
- / Pre-fabricated and proven solutions
- / Developed with a focus on safety, flexibility and standardisation
- / Global service



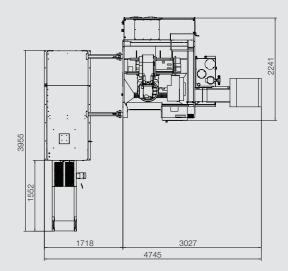
# /TECHNICAL DATA

| Description                      | IRB 1600-10/1.45            | IRB 2600-12/1.65 | IRB 2600-12/1.85 |
|----------------------------------|-----------------------------|------------------|------------------|
| Lengh                            | 3.947 mm                    | 3.947 mm         | 3.947 mm         |
| Width                            | 1.010 mm                    | 1.010 mm         | 1.010 mm         |
| Hight                            | 2.217 mm                    | 2.217 mm         | 2.217 mm         |
| Weight                           | 2.610 kg                    | 2.644 kg         | 2.644 kg         |
| Robot model                      | IRB 1600                    | IRB 2600         | IRB 2600         |
| Robot payload                    | 10 kg                       | 12 kg            | 20 kg            |
| Robot reach                      | 1.450 mm                    | 1.650 mm         | 1.850 mm         |
| ln–conveyor width and length     | 430 x 2.000 mm              | 430 x 2.000 mm   | 430 x 2.000 mm   |
| Out-conveyor width and<br>length | <sup>d</sup> 430 x 2.500 mm | 430 x 2.500 mm   | 430 x 2.500 mm   |
| Max object/workpiece<br>height   | 200 mm                      | 200 mm           | 200 mm           |
| Max belt load                    | 100 kg                      | 100 kg           | 100 kg           |
| Machine tool interface           | Profinet                    | Profinet         | Profinet         |

## MACHINE LAYOUT



FLOOR PLAN



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